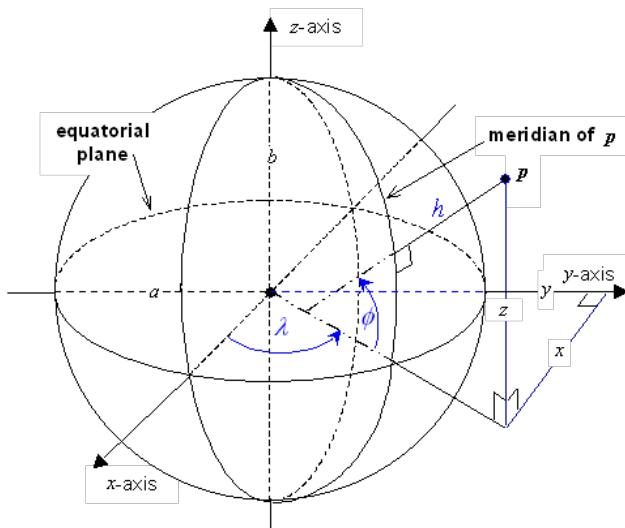


# X Y Z ↔ φ λ h

di Michele T. Mazzucato

L'origine del sistema di coordinate cartesiane ortogonali nello spazio X, Y, Z coincide con il centro geometrico dell'ellissoide utilizzato come superficie di riferimento per le coordinate di geografiche ellissoidiche  $\phi$ ,  $\lambda$ ,  $h$ . L'asse Z coincide con l'asse minore o di rotazione dell'ellissoide ed è positivo verso il Polo Nord, l'asse X giace nel piano equatoriale XY (origine delle latitudini) nell'intersezione con il piano meridiano XZ di Greenwich (origine delle longitudini) ed è positivo verso il meridiano di Greenwich e l'asse Y giace nel piano equatoriale XY, ortogonale all'asse X ed è destroso positivo.



da <https://standards.sedris.org/18026/index.htm>

Il *passaggio diretto* dalle coordinate geografiche ellissoidiche  $\phi$ ,  $\lambda$ ,  $h$  a quelle cartesiane ortogonali nello spazio X, Y, Z non presenta particolari difficoltà. Esso avviene mediante le seguenti relazioni:

$$\begin{aligned} X &= \left( \frac{a}{\sqrt{(1 - e^2 \sin^2 \phi)}} + h \right) \cos \phi \cos \lambda & Y &= \left( \frac{a}{\sqrt{(1 - e^2 \sin^2 \phi)}} + h \right) \cos \phi \sin \lambda \\ Z &= \left[ \frac{a}{\sqrt{(1 - e^2 \sin^2 \phi)}} (1 - e^2) + h \right] \sin \phi \end{aligned}$$

in cui **a** è il semiasse maggiore ed **e** l'eccentricità prima numerica dell'ellissoide di riferimento geodetico

Diversamente accade per il *passaggio inverso* dalle coordinate cartesiane ortogonali nello spazio X, Y, Z a quelle geografiche ellissoidiche  $\phi$ ,  $\lambda$ ,  $h$ .

Mentre, per la determinazione della longitudine  $\lambda$  si utilizza, generalmente, la relazione

$$\lambda = \arctan \frac{Y}{X} \pm 180^\circ$$

oppure la formula di Krakiwsky & Vanicek (1982) che la determina senza bisogno di definirne il segno e quindi il suo fuso, numericamente più stabile in vicinanza dei poli

$$\lambda = 2 \arctan \frac{Y}{X + \sqrt{X^2 + Y^2}}$$

Krakiwsky & Vaníček (1982)

oppure la formula di Vermeille (2004) con una stabilità numerica maggiore rispetto alla precedente

$$\lambda = \frac{\pi}{2} - 2 \arctan \frac{X}{\sqrt{X^2 + Y^2} + Y} \text{ per } Y \geq 0$$

$$\lambda = \frac{\pi}{2} + 2 \arctan \frac{X}{\sqrt{X^2 + Y^2} - Y} \text{ per } Y < 0$$

Vermeille (2004)

e per la determinazione dell'altitudine  $h$ , una volta ottenuta la latitudine  $\varphi$ , si utilizza

$$h = \frac{\sqrt{X^2 + Y^2}}{\cos \varphi} - N$$

oppure altre formule alternative come

$$h = \frac{Z}{\sin \varphi} - N(1 - e^2)$$

Bencini (1968)

$$h = \sqrt{X^2 + Y^2} \cos \varphi + Z \sin \varphi - a \sqrt{(1 - e^2 \sin^2 \varphi)}$$

Bowring (1985)

la determinazione della latitudine  $\varphi$ , invece, risulta più complicata in quanto nessuna relazione semplice la collega a  $X$ ,  $Y$ ,  $Z$ . Essa richiede tecniche indirette (o iterative) o metodi diretti (formule chiuse) di gran lunga più complessi di quelle indirette. In letteratura numerosi sono gli studi e le procedure proposte da vari autori (vedere tabella 1).

#### Simple Iteration

procedimento descritto in vari testi di geodesia come in Bomford, Guy (1899-1996) *Geodesy* (4<sup>a</sup> ed. 1980, p. 679)

$$\tan \varphi_1 = \frac{Z + \frac{a}{\sqrt{(1 - e^2 \sin^2 \varphi_0)}} e^2 \sin \varphi_0}{\sqrt{X^2 + Y^2}}$$

il procedimento iterativo inizia con il valore di  $\varphi$  fornito dalla  $\tan \varphi_0 \approx \frac{Z(1 - e^2)}{\sqrt{X^2 + Y^2}}$

in cui  $e'$  è l'eccentricità seconda numerica dell'ellissoide di riferimento geodetico

**Tabella 1**  
**Conversione cartesiane geocentriche ↔ geografiche ellissoidiche.**  
**Elenco alfabetico, non esaustivo, per autore**

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**NOTE**

- alcune forme dirette o chiuse (non iterative) mantengono tale proprietà solo per  $h=0$  (punto giacente sulla superficie di riferimento ellissoidica);
- Vincenty (1985) afferma che la prima soluzione a questo problema è stata data da Dörrie, Heinrich (1873-1955) in *Kubische und biquadratische Gleichungen* (1948);

